User Manual

LDP-CWL 90-10
(preliminary)

PicoLAS

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Rev. 2201

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Please pay Attention to all Safety Warnings!

Symbols used in this manual:


Risk of electrical hazard


Please pay special attention


Do not


Valuable information, remark

PicoLAS

FOCUSSING POWER TO THE POINT

LDP-CWL 90-10

Rev. 2001

Low nose wide range cw driver for High Power Laser Diodes

- Output current: 0.2 .. 90 A
- Compliance voltage: 0 .. 12 V
- Output power: 900 W
- Fast current extinction
- High precision: 70 mA current resolution
- Several protective features
- High efficiency

Product Description

The LDP-CWL 90-10 is one of the most versatile drivers from PicoLAS, offering a wide range from 200 mA to 90 A with a current setpoint resolution of less than 70 mA. For special applications a fast current extinction of less than 15 μs is implemented. The low nise and wide range is achieved by a combination of a switchmode regulator and an analogue post stage. The analogue and digital interface makes it easy to use.
Intended fields of application are laser soldering and welding as well as generic surface treatment and DPSS.
The innovative current regulation concept of the LDP-CWL 90-10 produces, compared to the commonly used linear regulation concept, considerably less losses. Hence, only one supply voltage is needed for the control logic and the power stage.

In order to shield your laser diode from damage, the LDP-CWL 90-10 features a number of powerful protective safeguards:

- Integrated Soft Start
- Overtemperature shutdown
- Enable/Disable input
- Driver status output
- Protection of the laser diode against reverse currents

Output current	0.2 .. 90 A
Compliance voltage	0 .. 12 V
Current ripple	< 1 %
Current overshoot	< 1 %
Analog modulation ($10\ A_{pp}$)	TBD**
Current settling time (full-scale)	TBD**
Current setpoint input	Analog or digital
Current monitor	25 A / V
Voltage monitor	Via digital interface
Interfaces	RS232 / CAN / BOB
Supply voltage	18 - 24 V DC
Max. power dissipation	TBD**
	Full brick size
Dimensions in mm	61 x 120 x 50
Weight	194 g
Operating temperature	0 to +55 °C

* Specifications measured with a fast recovery diode instead of a laser diode.
Technical data is subject to change without further notice.
** See manual for further details
*** Not available in current firmware revision

Optional Accessories: LDP-C BOB
PLB-21

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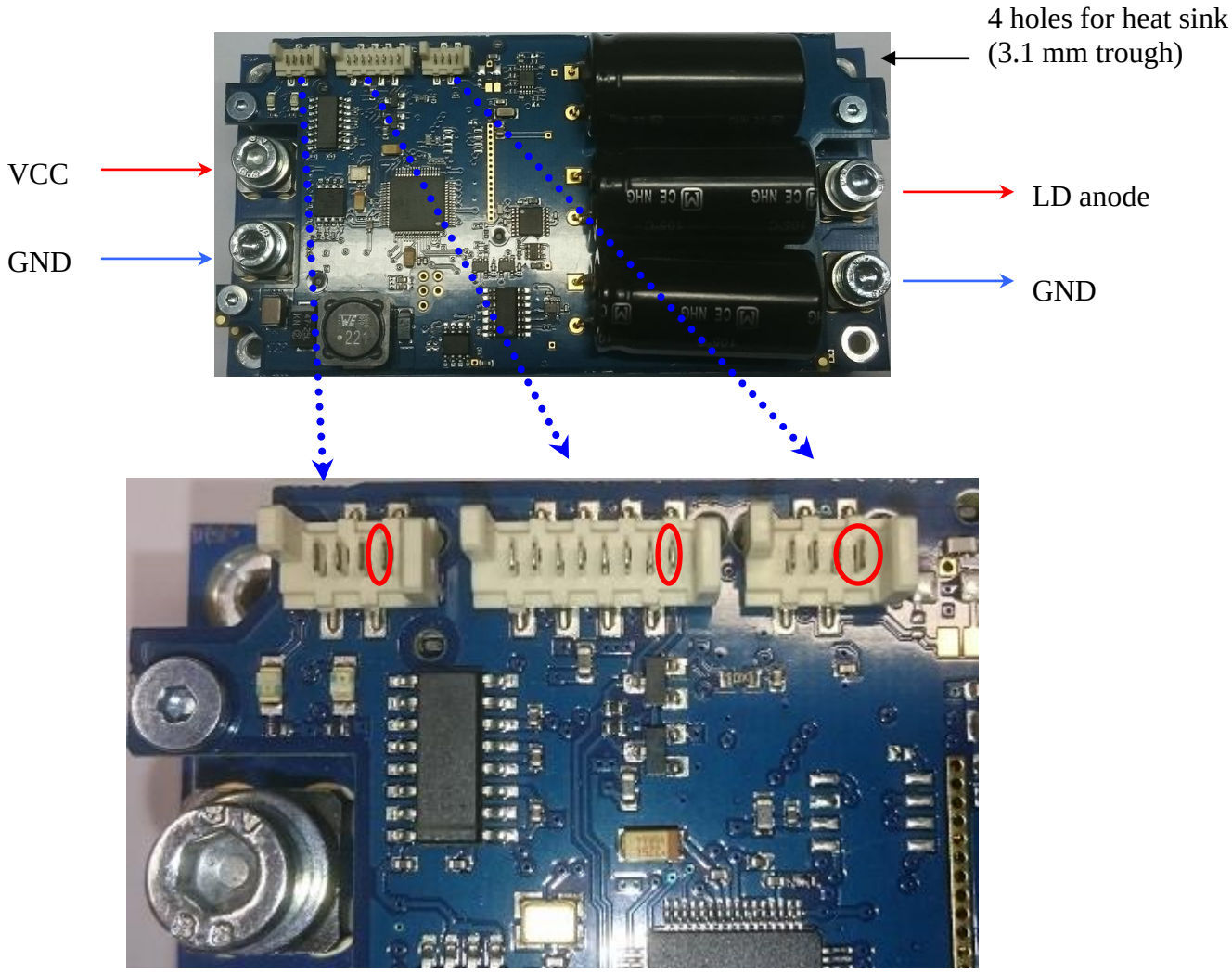
Description of Connections

All connectors on the LDP-CWL 90-10 are protected against ESD as described by the human body model.

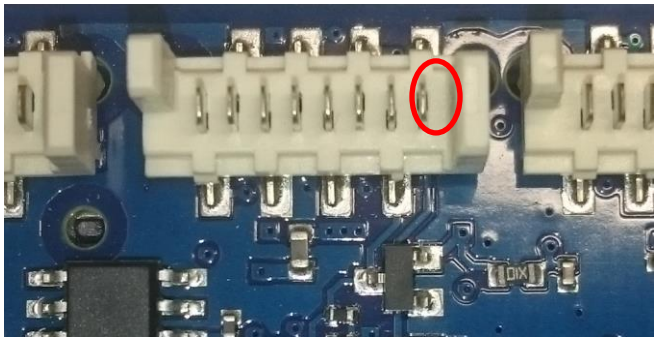
The following drawing shows all connections that are available to the user.



Left: RS-232 / PLB connector (pin 1 marked), Middle: LDP-C BOB connector (pin 1 marked), Right: CAN-Bus connector (pin 1 marked)

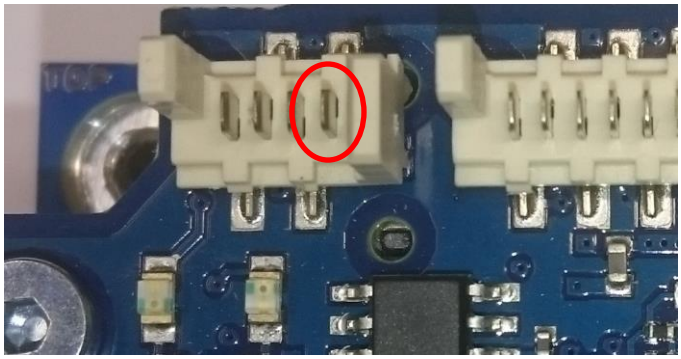
Connector	Description
VCC	Supply voltage 24 V
GND (next to VCC)	Supply ground
LD+	Positive laser diode output (anode)
GND (next to anode on the right side)	Negative laser diode output (cathode) ground. Do not use the input ground!
LDP-C BOB connector	Mini MOLEX Connector for analogue / TTL control of the driver (see below)
RS-232 / PLB-21 connector	Mini-MOLEX connector for RS-232 communication or the PLB-21 (see below)
CAN Bus	Provides a CAN bus interface corresponding to CAN 2.0 (not implemented in the preliminary version)

Pin Assignments and Description of the MOLEX Pin Header



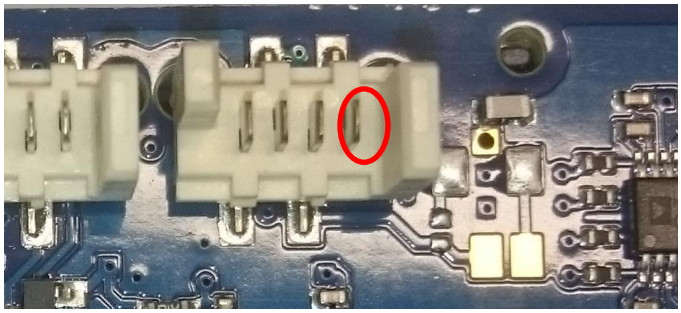
The connector is a MOLEX_908140008, a suitable female connector would be a MOLEX - 90327-0308 like Farnell 673160.

Pin Number	Description	Direction	Comments
1 (marked in red)	reserved		Do not connect!
2	reserved		Do not connect!
3	I-Soll	Input	Scale: depending on configuration
4	Enable-Ext	Input	0 V = disabled, 3.3 V = driver enabled
5	Pulser-Ok ("pulser" is used here as a synonym for driver)	Output	0 V = laser diode driver not ok **or** power up self test not passed yet; 3.3 V = driver ok / test passed
6	GND	Output	
7	I-Diode	Output	Current monitor output (20 A/V)
8 (left)	+ 3.3 V (via 10 R)	Output	Can be used to connect with pin 4 to enable the driver, please use a switch for safety reasons



The connector is a MOLEX_908140004, female connector MOLEX - 90327-0304 like Farnell 673146.

Pin Number	Description	Direction	Comments
1 (marked in red)	+12 V	Output	Only for the use with the PLB-21, prevent any overload or short! (max. 100 mA)
2	TXD	I/O	RS-232 standard serial interface
3	RXD	I/O	RS-232 standard serial interface
4 (left)	GND	Output	



The connector is a MOLEX_908140004, female connector MOLEX - 90327-0304 like Farnell 673146.

Pin Number	Description	Direction	Comments
1 (marked in red)	n.c.		Not connected
2	CAN +	I/O	CAN +
3	CAN -	I/O	CAN -
4 (left)	GND	Output	

How to get started (quick start without PLB-21)

Step	What to do	Note
1	Unpack your device.	
2	Connect a load to the output. Screw connectors are on the right side. Pay attention to the polarity when connecting a diode.	For tests the load might be a resistor or a dummy diode.
3	Apply the supply voltage. Connect the VCC input on the upper left to your power source (fix your wires with the screws at the connector).	Apply supply voltage of +24 V at "VCC" with respect to GND. Make sure there is no voltage surge that could destroy the unit when switching the power supply on!
4	Wait until "pulser-ok" is high ("pulser" is used here as a synonym for driver).	Pin 5 with respect to pin 6 must change from 0 V to 3.3 V.
5	Apply the current setpoint.	
6	Set enable pin "high".	Apply 3.3 V to pin 4 of the BOB connector. The current will ramp up now.
7	Check	If the driver is not properly cooled, it will shut down.

How to get started with a PLB-21

Step	What to do	Note
1	Unpack your device.	
2	Connect the PLB-21.	Use the PLB-21 pin header and the special cable.
3	Apply the supply voltage. Connect the VCC input on the upper left to your power source (fix your wires with the screws at the connector).	Apply any voltage between +15 V and +24 V to "VCC" with respect to GND. The voltage must be at least 7 V higher than the expected compliance voltage of the laser diode. Make sure there is no voltage surge that could destroy the unit when switching the power supply on!
4	Wait until "pulser-ok" is high (pin5). ("pulser" is used here as a synonym for driver.)	Pin 5 with respect to pin 6 must change from 0 V to 3.3 V.
5	Apply the current setpoint.	Use the PLB-21 to switch from external to internal setpoint and set the setpoint by turning the dial.
6	Set enable pin "high" (pin 4).	Apply 3.3 V to pin 4 of the BOB connector. The current will ramp up now.
7	Check	If the driver is not properly cooled, it will shut down.

Dos and Don’ts

Never make a short at the output. This will not do any harm to the laser driver but will result in an incorrect current measurement.

Keep the connection between power supply and driver as well as the connection between driver and laser diode as short as possible.

Mount the driver on an appropriate heat sink. The driver will shut down under overtemperature circumstances. Depending on the desired current a slight airflow across the black coils on top is necessary. Please keep the temperature of these devices below 85 °C

This diver uses a “low-side” current sensing technique. The GND of the VCC terminal is the not same as the GND of the LD terminal, hence a connection between these two is not recommended.

The driver is for cw operation only.

Never disconnect or connect the load while the driver is operational. This will destroy the driver and / or the connected load.

Make sure that the control ground is connected to the supply ground. Any unexpected current flow through the control board may damage the driver.

Never use the power stage without the assembled controlling unit!

Absolute maximum Ratings

- Supply voltage range: +24 V
- Maximum input current: 100 A
- Maximum laser diode output current: 90 A
- Maximum laser diode compliance voltage: 12 V (up to 18 Volts possible, but no support)
- BOB connector input and output voltages: 0 V to 3.3 V (terminals are 5 V proof)
- BOB connector output currents: 1 mA
- Auxiliary 3.3 V supply voltage output current: 30 mA (pin 8 of BOB connector planned for Rev 2.1)
- Auxiliary 12 V supply voltage output current: 100 mA (pin 1 of PLB-21 connector)
- Operating temperature: 0 .. 55 °C

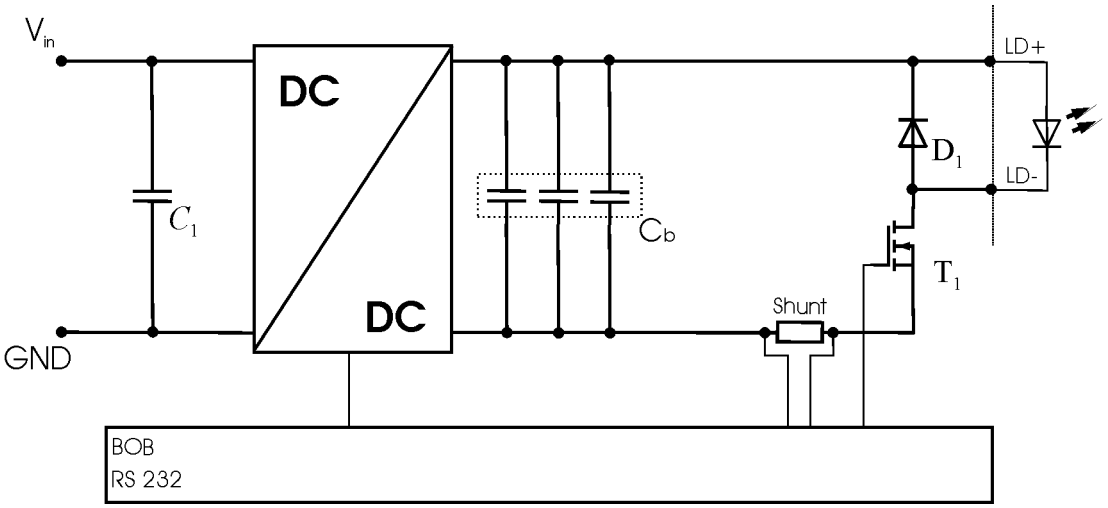
Ordering Options / Product Changes

- LDP-CWL 90-10 or LDP-CWL 90-10-**S50** yields the standard unit with the scaling 5 V = 90 A
- LDP-CWL 90-10-**S33**: Input scaling is 0 .. 3.3 V correspond to 0 .. 90 A. The first units were shipped with this scaling. If you require this furthermore, please order with the -S33 option.

  Note: This affects the analog input only.

Current Regulator

The driver is equipped with a linear current regulator, which can drive up to 90 A. The following diagram gives a simplified technical overview:



As shown in the diagram a DC-DC converter is used to generate the voltage required to drive the laser diode. It can be configured via software between 2 V and 20 V or controlled automatically.

Manual: When the voltage is chosen manually it must be at least 1.5 V higher than the laser diodes compliance voltage. This will decrease the rising edge of the output current. However, if it is not high enough, the driver will not be able to reach the set point current.

Auto: In this mode, the driver will set the voltage automatically to minimize the power losses in the output stage but will lead to a slower rising edge.

Current Limiter

The driver is equipped with a software based current limiter. This can be used to configure a maximum valid current setpoint (analog and digital) which cannot be overstepped.

External Setpoint

An external voltage can be applied to the driver which defines the setpoint current. The scaling of this voltage depends on the version of the driver. See datasheet for more information.

In order to switch between external and internal setpoint the bit 6 of the LSTAT register must be altered. Please note that this only works if the driver is disabled!

The external setpoint voltage is converted by an analog to digital converter into a digital value. The resolution of this converter is 10 bit. This may lead to some current jitter as this resolution is not equal to the current resolution of 0.1 A.

The input impedance on this input pin is greater or equal to 10 kOhms.

Test Load

A common method to test the driver is to connect a regular silicon rectifier diode to the driver output. Attention has to be paid to the junction capacitance of the diode. Only fast recovery diodes (or similar) have a low parasitic capacitance as laser diodes have. To achieve reasonable test results the parasitic elements of the test diode and the connection must be very similar to a laser diode approach. Regular silicon rectifier diodes have a junction capacitance of several microfarads and are not a suitable test load! The use of these diodes will yield in incorrect current measurement at the pulse edges!

Power Supply

The power supply must be able to cover the output power plus the internal power losses (please see next section).

Cooling

The driver has to be mounted on a heat sink to ensure proper operation and prevent an overtemperature shutdown. It produces thermal losses depending on the selected voltage and output current. The actual losses can be estimated by using the following equation:

$$P_L = 0.72 \cdot I_{in+} (V_{dcdc} - V_{LD}) \cdot I_{LD+} P_S$$

where

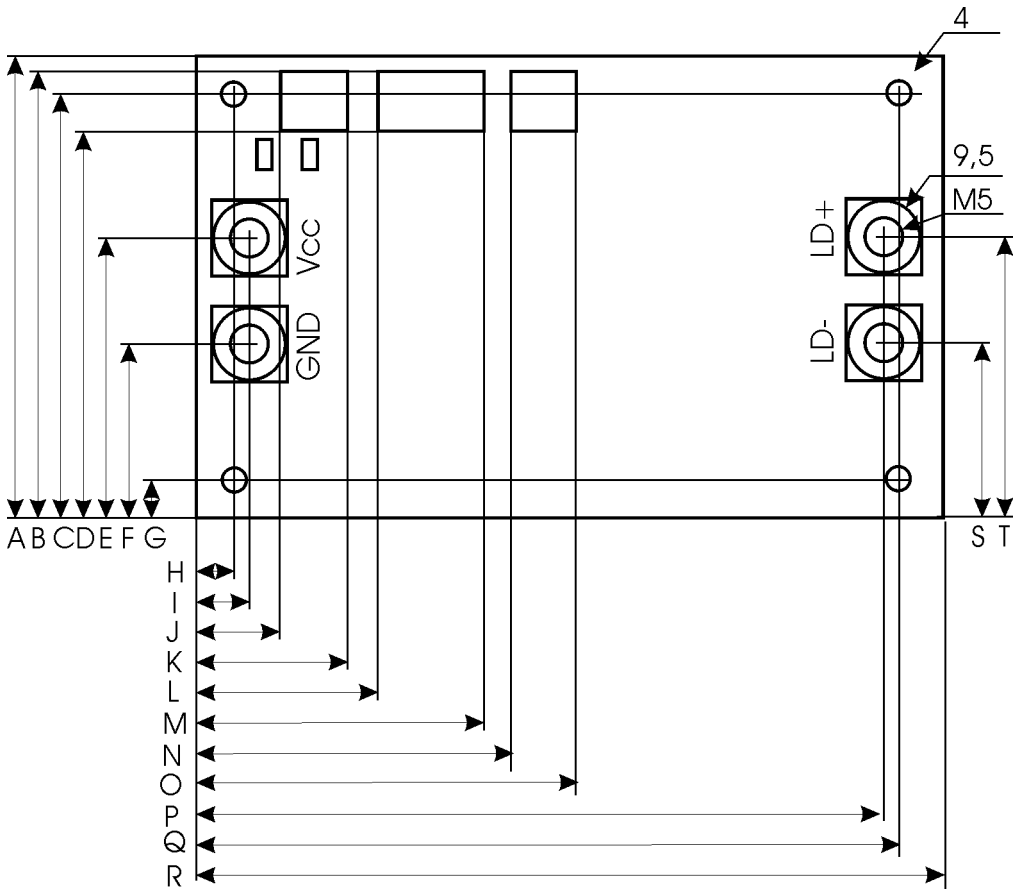
P_L	Thermal dissipation loss in W
I_{in}	Input current
V_{dcdc}	Capacitor voltage in V
V_{LD}	Compliance voltage of the LD in V
I_{LD}	Laser diode current
P_S	Static operation losses ~ 5 W

Over temperature Shutdown

To protect itself, the driver automatically shuts down if its temperature rises above 80 °C. This condition is latched and the appropriate bit in the ERROR register is set. To re-enable the driver the ENABLE pin must be toggled (set low and then high).

Mechanical Dimensions

All dimensions are in millimetres (mm).



Position (vertical)	Dimension (mm)		Position (horizontal)	Dimension (mm)
A	61		H	4.8
B	59.6		I	6.6
C	55.9		J	9.3
D	51.7		K	18.3
E	38.1		L	20.6
F	22.8		M	34.8
G	5.1		N	45.2
S	16.2		O	53
T	32.8		P	113.3
			Q	115
			R	120

Power on Self Test

Each time the driver is powered up, it performs a test of its internal safety features. The driver cannot be enabled until a self test has been performed successfully. The PULSER_OK signal will be pulled high when the test has been successful.
The test will take less than 5 seconds, but can take up to 15 seconds due to internal time-outs if any failures are detected.

Controlling the Driver

The driver can be operated stand alone, with a PLB-21 or a PC connected to it via a serial link (RS-232 interface, for USB you need an USB RS-232 adaptor). It remembers all settings from the last time it had been powered on, unless configured to load default values on power-on. In latter case it loads pre-configured settings each time the power is applied. Connecting a digital control to the driver does not alter the internal settings.

No digital control (factory default)
If no digital control (PLB-21 or serial link to PC) is attached, only the BOB connector could be used to control the driver. If configured so, the pin 10 at the BOB connector ("$I_{setpoint}$") can be used to control the setpoint current. To enable the output pin 7 at the BOB connector ("ENABLE") must be set HIGH. If an error occurs (e.g. overtemperature), the driver will be disabled and the pin 1 of the BOB connector ("PULSER_OK") is pulled low. The "enable" pin has to be toggled to enable the driver again.

PLB-21
If a PLB-21 is attached to the driver, it can be used to control the behavior of the driver. The PLB-21 may ask for a driver to download. This must be confirmed with "yes" in order for the PLB-21 to work properly. This must always be done when the PLB-21 was connected to any other PicoLAS product. After the download all operating parameters can be accessed using the PLB-21. For a detailed description see chapter PLB-21 below.

RS-232
If the driver is connected to a PC using a serial cable, all operating parameters can be accessed via a serial RS-232 terminal program or the PicoLAS protocol. The PLB-21 is automatically disabled if a serial connection is established. For a detailed description of the serial text protocol and the PicoLAS protocol see below.

PC
If the driver is connected to a PC, all operating parameters can be accessed via a serial RS-232 terminal program or the PicoLAS protocol. For a detailed description of the serial text protocol and the PicoLAS protocol see below.

Controlling the Driver using a PLB-21

When the PLB-21 is connected the first time to the driver, the user is asked to download a new firmware driver. This must be confirmed with “yes” in order for the PLB-21 to work properly.

Menu Structure

The following diagram shows the structure of the PLB-21 menu which affects the driver. All entries are described in detail. All other menu entries are described in the PLB-21 manual. For detailed instructions see the PLB-21 manual.

Menu root

- Pulsgen
  - Cur(ext/int)
  - Cur Limit
  - Cap
- Config
  - Current
  - VCap mode
-
- Temp
  - Temp 1
  - Temp 2
  - Temp 3
  - Temp Off
- Defaults
  - Def. pwron
  - Load defaults
  - Save defaults

Pulsgen

In this menu the setpoint current can be modified.

Cur (ext/int)
This value defines the setpoint current.
When using the internal setpoint, the value can be modified by the user.
When using the external setpoint, the value shown is measured value supplied at pin 3 of the BOB connector. The display is updated every few seconds, so it is not accurate when using analog modulation.

Cur Limit
This value defines the software current limitation value. Please see section “Current Limiter” for more details.

Cap
This value defines the precharge voltage for the linear current regulator. In the manual mode, this value can be modified.

Config

Current
The driver can either use an internal digital set point or an external analogue signal. This can be set here

VCap mode
This can be set to manual or auto.

Temp

The driver is equipped with several an onboard temperature sensors. The actual measured temperatures of the PCB as well as the shutdown temperature can be monitored here.

Defaults

The driver can load a default setting each time it powers up or the user commands it to do so. This is done within this submenu.

Def. pwron
When enabled, the driver loads the saved settings each time it powers up.

Load
When activated via turning the Jogdial or the ENTER key all internal registers are changed to the previously saved values. The output stage has to be re-enabled via the L_ON bit or the FIRE Key afterwards

Save
When activated via turning the Jogdial or the ENTER key all internal registers are stored into an internal EEprom for later usage.

If an Error occurs

If an error occurs during operation the pulse output is switched off, the “pulser_ok_ext” signal on the BOB connector is pulled low and a message is displayed on the PLB-21. If no other action is described on the display, a toggle of the ENABLE pin resets the error condition and re- enables the driver.

Controlling the Driver via a PC

Introduction

When the driver is connected to a PC, it allows communications over a serial text interface as well as the PicoLAS protocol. While the text interface is designed for communication with a terminal program, the PicoLAS protocol is designed as a system interact protocol.

The switching between the two protocols occurs automatically as soon as the driver receives a certain sequence. The corresponding commands are:

- **PING** for the PicoLAS protocol
- "**init**" followed by <Enter> for the text interface

Description of the RS-232 Interface

The driver implements a standard RS-232 interface. It can be connected to a PC using a three-wire connection. For USB connection you need a USB RS-232 adaptor (USB-serial adapter).

The connection settings are:

Baud rate	115200
Data bits	8
Stop bits	1
Parity	even

The Serial Text Interface

The following section describes the structure and the commands of the text interface.

Structure

Every command that is sent to the driver must be completed with a CR (Carriage Return = Enter). It consists of a command word followed by one or more parameters. If the command has been executed successfully a “00” is sent, otherwise a “01”. If there is an error pending, the response will be “10”, otherwise “11”. If the command requires an answer parameter, this parameter is sent before the confirmation is given.

Exampe1:

The user would like to read out the actual setpoint current:

User input:	gcur<Enter>
Output of the driver:	12.2<CR><LF>
	00<CR><LF>

Example 2:

The user would like to set a new setpoint current:

User input:	scur 25.7<Enter>
Output of the driver:	25.7<CR><LF>
	00<CR><LF>

Input is done in ASCII code and is case sensitive. Every terminal can be used which supports this standard.

Commands for the serial text interface

The following table contains a command reference for the driver.

Command	Parameter	Answer	Description
scur	Current in A	--	Sets the pulse current to the indicated value. A dot is used as decimal point. No more then one decimal place is used! (12.225 is the same as 12.2)
gcur	--	Current in A	Outputs the present output current
gcurmin	--	Current in A	Outputs the minimum output current
gcurmax	--	Current in A	Outputs the maximum output current
scurlimit	Current in A	Current in A	Sets the current limiter to the given value in A. A dot is used as decimal point. No more then one decimal place is used! (12.225 is the same as 12.2)
gcurlimit	--	Current in A	Outputs the actual current limiter value
gcurlimitmin	--	Current in A	Outputs the minimum current limiter value
gcurlimitmax	--	Current in A	Outputs the maximum current limiter value
cur_ext	--	--	Use external current setpoint
cur_int	--	--	Use internal current setpoint
slstat	32 bit number	--	Sets the LSTAT register to the value
glstat	--	32 bit number	Outputs the LSTAT register
gserial	--	serial number	Returns the device serial number
gname	--	device name	Returns the devices internal name
ghwver	--	hardware version	Prints out the hardware version
gswver	--	software version	Prints out the software version
ps	--	current settings	Prints out an overview of all settings
loaddefault	--	--	Loads previously saved settings
savedefault	--	--	Saves the current settings as defaults
enautoload	--	--	Enables the autoload feature
disautoload	--	--	Disables the autoload feature
gtemp1	--	Temperature in °C	Returns the temperature of sensor 1
gtemp2	--	Temperature in °C	Returns the temperature of sensor 1
gtemp3	--	Temp. in °C	Returns the temperature of sensor 1
gtempoff	--	Temperature in °C	Returns the temperature at which the device will shut down

Command	Parameter	Answer	Description
gtemphys	--	Temperature in °C	Returns the temperature at which the device will restart after thermal shutdown
gtempwrn	--	Temperature in °C	Returns the temperature at which the device will warn about reaching its thermal limit
gadcidiode		Current in [A]	
gadcudiode	--	Voltage in [V]	Returns the actual measured compliance voltage
gadcuin	--	Voltage in [V]	Returns the actual measured supply voltage
gadcvcap	--	Voltage in [V]	Returns the actual measured capacitor voltage
gadcvds	--	Voltage in [V]	Returns the actual measured voltage drop over the linear stage

If an Error Occurs

If an error occurs during operation the driver output is switched off and the return value of a command is no longer “00” or “01” but “10” or “11”. Errors have to be acknowledged with a toggle of the ENABLE signal (switch off and on again), otherwise switching on again of the LDP-CW output is not possible. For more details see the description of the ERROR register.
To retrieve the error, use the **gerr** command for the content of the ERROR register or the **gerrtxt** command for a human readable form.

The PicoLAS Protocol

The following section describes the structure and valuable commands of the PicoLAS protocol.

Structure

Each transmission consists of 12 bytes – called a frame in the following – that must be sent consecutively. Otherwise the system times out and the transmission must start again from the beginning.

A frame has a fixed structure. The first two bytes describe the command, the following eight bytes the parameters, followed by one reserved byte and one checksum byte. The checksum is calculated out of the first 11 bytes that are linked by a bitwise XOR.

Thus a frame has the following structure:

Byte	Meaning
1	Bit 8-15 of the command
2	Bit 0-7 of the command
3	Bit 56-63 of the parameter
4	Bit 48-55 of the parameter
5	Bit 40-47 of the parameter
6	Bit 32-39 of the parameter
7	Bit 24-31 of the parameter
8	Bit 16-23 of the parameter
9	Bit 8-15 of the parameter
10	Bit 0-7 of the parameter
11	Reserved, always 0x00
12	Checksum

A properly received frame must be acknowledged by the recipient with an answer that is also a frame. If the acknowledgement does not occur the command has not been processed and the sending procedure should be repeated.

If the recipient recognizes the command as valid, but not the parameters, it will answer with an ILGLPARAM (0xFF12) as command.

In the case the recipient receives an invalid command it will answer with UNCOM (0xFF13).

If a faulty checksum is recognized, the answer is RXERROR (0xFF10). If this error occurs often, the connection should be checked.

Using the REPEAT (0xFF11) command the recipient can instruct the sender to send the most recent frame again.

General Commands

The following list contains an overview of the general commands that are supported by every product from PicoLAS making use of this protocol. The explanation of the individual commands is given further below.

Command Name	Sent Frame		Answer Frame	
	Command	**Parameter**	**Command**	**Parameter**
PING	0xFE01	0	0xFF01	0
IDENT	0xFE02	0	0xFF02	ID
GETHARDVER	0xFE06	0	0xFF06	Version
GETSOFTVER	0xFE07	0	0xFF07	Version
GETSERIAL	0xFE08	0 … 20	0xFF08	Refer to description
GETIDSTRING	0xFE09	0 … 20	0xFF09	Refer to description

PING
This command is used to determine the presence of a connected driver and to initialize its interface. It does not change any registers. The command parameter is always 0, the answer parameter as well.

IDENT
This command is used to determine the device ID of an attached recipient. It has no effect on the condition of the recipient. The parameter is always 0. The answer contains the ID.

GETHARDVER
Instructs the driver to send the version number of its hardware. The parameter is always 0. The answer contains the hardware version number. The format of the answer is: 0x000000<major><minor><revision>. In other words: one byte for each of the three elements of the version number.
As example, version 1.2.3 has the parameter 0x000000010203.

GETSOFTVER
Instructs the driver to send the version number of its firmware. The parameter is always 0. The answer contains the software version of the recipient. The format of the answer is: 0x000000<major><minor><revision>. In other words: one byte for each of the three elements of the version number.
As example, version 2.3.4 has the parameter 0x000000020304.

GETSERIAL
Instructs the driver to send its serial number. If 0 is sent as parameter, the answer contains the number of (ASCII) digits of the serial number. Otherwise the respective position of the serial number is sent in ASCII format.

GETIDSTRING
Instructs the driver to send its name. If 0 is sent as parameter, the answer contains the number of digits of the string. Otherwise the respective position of the serial number is sent in ASCII format.

Commands for the Driver

The following table contains a list of the commands which the LDP-CW supports in addition to the generally applicable commands. An explanation of the individual commands and its parameters follows afterwards.

Command	Sent Frame		Received Frame	
	Command	**Parameter**	**Command**	**Parameter**
GETTEMP	0x0100	0	0x8100	16 bit signed integer
GETTEMP1	0x0101	0	0x8100	16 bit signed integer
GETTEMP2	0x0102	0	0x8100	16 bit signed integer
GETTEMP3	0x0103	0	0x8100	16 bit signed integer
GETTEMPOFF	0x0104	0	0x8100	16 bit signed integer
GETTEMPHYS	0x0105	0	0x8100	16 bit signed integer
GETLSTAT	0x0200	0	0x8200	32 bit unsigned integer
SETLSTAT	0x0201	Refer to description	0x8200	32 bit unsigned integer
GETERROR	0x0300	0	0x8300	32 bit unsigned integer
CLEARERROR	0x0301	0	0x8300	0
GETVCAP	0x0400	0	0x8400	16 bit unsigned integer
GETVCAPMIN	0x0401	0	0x8400	16 bit unsigned integer
GETVCAPMAX	0x0402	0	0x8400	16 bit unsigned integer
SETVCAP	0x0403	Refer to description	0x8400	16 bit unsigned integer
SETCUR	0x0500	Refer to description	0x8500	16 bit unsigned integer
GETCUR	0x0501	0	0x8500	16 bit unsigned integer
GETCURMIN	0x0502	0	0x8500	16 bit unsigned integer
GETCURMAX	0x0503	0	0x8500	16 bit unsigned integer

Command	Sent Frame		Received Frame	
SETCURLIMIT	0x0504	Refer to description	0x8500	16 bit unsigned integer
GETCURLIMIT	0x0505	0	0x8500	16 bit unsigned integer
GETCURLIMITMIN	0x0506	0	0x8500	16 bit unsigned integer
GETCURLIMITMAX	0x0507	0	0x8500	16 bit unsigned integer
GETADCUDIODE	0x0600	0	0x8600	16 bit unsigned integer
GETADCIDIODE	0x0601	0	0x8600	16 bit unsigned integer
GETADCVCAP	0x0602	0	0x8600	16 bit unsigned integer
GETADCUIN	0x0603	0	0x8600	16 bit unsigned integer
GETADCUSD	0x0603	0	0x8600	16 bit unsigned integer
LOADDEFAULT	0x0700	0	0x8700	0
SAVEDEFAULT	0x0701	0	0x8700	0

Description of the individual Commands

GETTEMP
The return value contains the actual measured temperature of the driver. It represents the maximum of the tree individual sensors, which can also be monitored. It is scaled in 0.1 °C.

GETTEMP1
The return value contains the actual measured temperature of the first temperature sensor. It is scaled in 0.1 °C.

GETTEMP2
The return value contains the actual measured temperature of the second temperature sensor. It is scaled in 0.1 °C.

GETTEMP3
The return value contains the actual measured temperature of the third temperature sensor. It is scaled in 0.1 °C.

GETTEMPOFF
The return value contains the overtemperature shutdown border. If the driver reaches this temperature, it will shutdown itself. It is scaled in 0.1 °C.

GETTEMPHYS
The return value contains the temperature to which the driver must cool down before it can be re-enabled. It is scaled in 0.1 °C.

GETLSTAT
This command returns the value of the LSTAT register. For a complete description of this register see below.

SETLSTAT
This command sets the LSTAT register to the given value. The return value contains the new register value.

GETERROR
This command returns the value of the ERROR register. For a complete description of this register see below.

GETVCAP
The return value contains the actual voltage setpoint value in steps of 0.1 V.

GETVCAPMIN
The return value contains the minimum setpoint value in steps of 0.1 V.

GETVCAPMAX
The return value contains the maximum setpoint value in steps of 0.1 V.

SETVCAP
This command sets the current setpoint to the given value in steps of 0.1 V. The value must be within the borders defined by the minimum and maximum current values given by the *GETVCAPMIN* and *GETVCAPMAX* command.
The return value contains the actual set point value.

SETCUR
This command sets the current setpoint to the given value in steps of 0.01 A. The value must be within the borders defined by the minimum and maximum current values given by the *GETCURMIN* and *GETCURMAX* command.
The return value contains the actual setpoint value.

GETCUR
The return value contains the actual setpoint value in steps of 0.1 A.

GETCURMIN
The return value contains the minimum setpoint value in steps of 0.1 A.

GETCURMAX
The return value contains the maximum setpoint value in steps of 0.1 A.

GETSOLLLIMIT
The return value contains the actual configured current limiter value in steps of 0.1 A.

SETSOLLLIMIT
This command sets the current limiter to the given value in steps of 0.01 A. The value must be within the borders defined by the minimum and maximum current values given by the *GETCURLIMITMIN* and *GETCURLIMITMAX* command.
The return value contains the actual current limiter value.

GETSOLLLIMITMIN
The return value contains the minimum current limiter value in steps of 0.1 A.

GETSOLLLIMITMAX
The return value contains the maximum current limiter value in steps of 0.1 A.

SAVEDEFAULTS
This command saves all settings to an internal EEProm.

LOADDEFAULTS
This command loads previously saved settings into the driver.

GETADCUDIODE
The return value contains the actual measured compliance voltage of the connected load. It is measured in steps of 0.1 V.

GETADCIDIODE
The return value contains the actual measured output current of the driver. It is measured in steps of 0.1 A. Please note that this is not an independent measurement and cannot be used to verify the output current.

GETADCVCAP
The return value contains the actual measured capacitor voltage. It is measured in steps of 0.1 V.

GETADCUIN
The return value contains the actual measured supply voltage. It is measured in steps of 0.1 V.

GETADCUSD
The return value contains the actual measured linear drop voltage. It is measured in steps of 0.1 V.

Register Description

Description of the LSTAT Register

The following list contains a description of the individual LSTAT bits. These can be read with GETLSTAT and written with SETLSTAT. With SETLSTAT a complete 32 bit word must always be written. Thus, to change individual bits, first the register must be read out with GETLSTAT, and then the desired bits changed and finally passed back to the driver with SETLSTAT.

Bit	Name	Read/Write	Meaning
0	ENABLE_IN	Read	When this bit is set to “1” it indicates that the external enable is given. (Read only)
1	PULSER_OK	Read	Indicates that the driver is in no error condition.
2	DEFAULT_ON_PWR ON	Read/Write	When “1” the driver will load the default values at each power-up.
3	Reserved	Read	Reserved
4	ENABLED	Read	When “1” the drivers current output is enabled
5	ENABLE_LOCK	Read	When “1” the driver will not be able to generate any current. Set the enable signal to low.
6	ISOLL_EXT	Read/Write	When “1” the external setpoint current is used. Only modifiable when ENABLE_OK is “0”.
7	VCAP_Mode	Read/Write	When “1” the driver will set the Vcap voltage automatically
8-31	Reserved	Read	Reserved

Description of the ERROR Register

The following list contains a description of the individual bits in the ERROR register. If the bit is a “1” it will deactivate the unit output.

The bits 1-3 and 5 are set during the power on self test. They can not be cleared by the ENABLE pin or the CLEARERROR command. If one of these bits is set, the supply voltage should be switched off and on again. If the error persists, the driver needs to be repaired.

Bit	Name	Read/Write	Meaning
0	CRC_DEVDRV_FAIL	Read	Indicates that the internally stored PLB-21 driver is invalid. The driver can still be used, but it is impossible to download the driver into the PLB-21.
1	CRC_DEFAULT_FAIL	Read	Indicates that the internal default registers are corrupt. The default values should be re- saved.
2	CRC_CONFIG_FAIL	Read	Indicates that the internal configuration register is corrupt. If this error persists, the driver needs to be repaired.
3	Reserved	Read	Reserved
4	CRC_ISOLLCAL_FAIL	Read	Indicates that the internal calibration register is corrupt. If this error persists, the driver needs to be repaired.
5	TEMP_OVERSTEPPED	Read	Indicates that the maximum operating temperature was overstepped.
6	TEMP_HYSTERESIS	Read	Indicates that the driver is cooling down after an overtemperature shutdown. The driver cannot be re-enabled until this bit flips back to “0”.
7	TEMP_WARNING	Read	Indicates that the operation temperature is near the shutdown temperature.
8	VCC_FAIL	Read	Indicates an overtemperature shutdown of the output stage.
9	FAILED_TO_LOAD_DEFAULTS	Read	Indicates that the last attempt to load the default values failed.
10	I2C_EEPROM_FAIL	Read	Indicates that there is an internal I2C bus error. If this error persists after a power cycle the device must be repaired.

Bit	Name	Read/Write	Meaning
11	I2C_DAC_FAIL	Read	Indicates that there is an internal I2C bus error. If this error persists after a power cycle the device must be repaired.
12	I2C_WR_FAIL	Read	Indicates that there is an internal I2C bus error. If this error persists after a power cycle the device must be repaired.
13	I2C_RD_FAIL	Read	Indicates that there is an internal I2C bus error. If this error persists after a power cycle the device must be repaired.
14-16	TEMP_SENSOR_FAIL	Read	Indicates that the corresponding temperature sensor is not working properly
17	ENABLE_POWERON	Read	Indicates that the ENABLE pin of the BOB connector was high during power-on. Only valid if ENABLE_EXT the LSTAT register is set to “1”.
18	Reserved	Read	Reserved
19	PWM_MAX_ERROR	Read	This indicates that the internal DC-DC controller has reached its maximum duty cycle and was unable to reach the programmed setpoint voltage. Check if supply voltage is at least 5V greater than the selected capacitor voltage.
20-31	Reserved	Read	Reserved